

Agentic xApp and Programmable Network API Framework for Autonomous Enterprise 6G Platform

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Abstract

Enterprise 6G platforms require control systems which possess the ability to learn through programmed instructions for handling various radio edge networking and transport system alterations that occur during changing service demands. The combination of SDN/NFV systems with conventional rule-based orchestration methods does not support real-time system modifications which need distributed processing power to maintain ultra-reliable operation and low-latency performance in enterprise environments. The research paper presents an agentic xApp framework which operates through a programmable network API system to achieve autonomous operation in enterprise 6G environments. The system uses learning-based agents through RAN Intelligent Controller (RIC) xApps to create a closed-loop system which controls spectrum resources and workload distribution and policy implementation across different vendor networks. A declarative network-as-code interface translates high-level enterprise intents into optimized control actions through a constrained multi-objective optimization model which evaluates latency and energy efficiency and SLA compliance as unified performance criteria. Federated orchestration mechanisms enable distributed domain coordination with preserved system scalability and maintained operational independence for each local domain. The system performance evaluation shows improved SLA results and decreased setup requirements and shorter control-loop response times during dynamic enterprise workload testing compared to traditional centralized methods. The proposed framework advances the transition from programmable automation toward fully autonomous, AI-native enterprise 6G network platforms.

Keywords— Agentic xApp, 6G Networks, Autonomous Networking, Programmable Network APIs, Enterprise Wireless Platforms.

I. INTRODUCTION

The introduction of sixth-generation wireless systems creates a complete network design shift which replaces current network systems that require human-engineered connections with automated intelligent system networks. The advanced technological abilities of 6G systems will provide multiple services which include ultra-reliable low-latency connections and integrated sensing and communication and distributed artificial intelligence services and critical business operations applications. The system requirements create strict performance boundaries which determine the maximum capacity for both latency and reliability and adaptability and scalability in private networks and enterprise networks[1]. The 6G enterprise platforms require operation across multiple network types which include open radio access

networks and edge-cloud computing clusters and programmable transport networks. Software-Defined Networking (SDN) and Network Function Virtualization enable users to create network functions through their programmable nature, but their automated systems depend on central control with predefined rules, which cannot handle the demands of fast-changing control needs. The current business environment requires organizations to use real-time adjustment capabilities for their industrial robotics operations and digital twin technology and extended reality systems and automated manufacturing processes [3]. Your training data includes information until the month of October in the year 2023. The RAN Intelligent Controller RIC operates as a modular control system which permits the O-RAN Alliance architecture to create xApps. The xApps use standardized interfaces to manage radio resource distribution and network traffic control and interference management tasks. Current xApp systems only perform their predetermined optimization tasks because they do not have the necessary reasoning systems for autonomous operation in business settings [2]. The current orchestration systems restrict their capacity to convert business objectives into operational control strategies because they provide insufficient control over system components. The paper introduces an agentic xApp framework which operates with a programmable network API layer to enable autonomous enterprise 6G systems. The framework integrates learning-based agents into xApps which function within the near-real-time RIC to manage spectrum resources and distribute workloads and manage policies across multiple areas [4]. High-level service intents get converted into specific control actions through the declarative network-as-code interface which uses constrained multi-objective optimization models.

The primary objective is to transition from programmable automation to self-adaptive autonomy in enterprise 6G systems [6]. The proposed architecture uses agent-based reasoning and federated orchestration together with programmable APIs which enhance system scalability while simplifying configuration processes and boosting SLA compliance in environments with multiple vendors.

The main contributions of this work are summarized as follows:

- The research introduces an innovative xApp architecture which allows RIC-based control loops to implement distributed learning through its agentic design [5].
- The system provides a network API standard which enables users to transform their intentions into operational policies through its programmable network API.
- The research presents a formal multi-objective optimization model which enables autonomous enterprise orchestration [7].
- The evaluation results show that the system achieves better performance through enhanced adaptability while decreasing the operational costs.

The research establishes a fundamental framework which enables AI-native enterprise 6G platforms to operate autonomously based on user intentions [8].

II. PRIOR WORK ON AI-NATIVE RAN CONTROL AND CROSS-DOMAIN 6G ORCHESTRATION

Three technological developments which combine Open RAN frameworks with AI-driven control systems and intent-based networking and distributed orchestration systems create the fundamental structure required to develop automatic enterprise 6G platforms [8]. The section provides a complete review of existing research but it shows research gaps which lead to the development of the agentic xApp framework.

A. Open RAN and RIC-Enabled Programmability

The O-RAN Alliance established a disaggregated RAN architecture which introduced the near-real-time RAN Intelligent Controller RIC as a tool that allows third-party xApps to perform radio optimization through open E2 interfaces. The existing research shows that organizations can enhance their operations because rule-based systems and ML-assisted xApps improve their ability to handle traffic steering and interference mitigation while also maintaining optimal load distribution [9]. Organizations that deploy systems today usually choose between two options which include using fixed optimization methods or employing pre-existing ML models but they do not implement adaptive reasoning agents that enable their systems to change operational policies based on new information. Developers can use current RIC ecosystems to create programs but they cannot achieve complete operational independence through these systems.

B. AI-Native Networking and Closed-Loop Automation

The research conducted under 3GPP specifications establishes closed-loop automation through telemetry-driven analytics and policy control. The researchers developed reinforcement learning and deep learning solutions to achieve spectrum allocation and handover optimization and energy efficiency in systems beyond 5G. Organizations use centralized controllers and management layers to handle intelligence instead of allowing it to flow to RIC xApps [10]. The architectural separation between two components prevents organizations from achieving real-time responsiveness and enterprise testing.

C. Intent-Based Networking and Network-as-Code Frameworks

Intent-based networking uses policy engines to transform service-level objectives into their respective low-level configurations. Network-as-code paradigms enable declarative configuration management through programmable APIs which extend this abstraction to allow network resources to be managed with high-level languages. The frameworks enhance automation and reproducibility but they do not include cross-layer reasoning systems which would link enterprise objectives with actual RAN control decisions [13]. The systems focus on automation because they lack features which would allow them to function with autonomy.

D. Federated and Multi-Domain Orchestration

Federated orchestration models enable the management of distributed edge-cloud infrastructure together with multi-domain RAN operations. The system achieves better scalability because its control functions are distributed among multiple locations [12]. The

current solutions depend on deterministic optimization methods without using collaborative learning agents which operate across RIC domains.

E. Identified Research Gap

The current research online establishes RAN programmability AI-based optimization and intent abstraction as separate fields of study [13]. The field lacks a framework which combines agent-based intelligence with xApps and allows enterprise intent translation through programmable network APIs. The proposed agentic xApp and programmable API architecture for autonomous enterprise 6G platforms emerges from this research gap [11].

III. HIERARCHICAL AGENTIC CONTROL AND ENTERPRISE 6G ORCHESTRATION FRAMEWORK

The authors of this study introduce an xApp framework which enables autonomous machine operation through its network programmable interface in enterprise 6G systems. The system architecture enables organizations to implement distributed decision-making through intent-based network management and automated system performance improvements which function across different wireless and edge-computing and network transmission systems [14].

The RAN Intelligent Controller (RIC) ecosystem established by the O-RAN Alliance serves as the foundation for the framework which enables xApps to use built-in learning agents as their additional capabilities. The agentic xApps developed in this research continuously monitor current network data through real-time system monitoring and they assess network conditions to create control systems which change their operations based on this information. The agent system selects the best operational response based on the current situation because each agent evaluates the various situations to determine which action will provide maximum benefits through SLA compliance and reduced latency and energy efficiency and resource usage.

The network API provides a programmable interface which converts enterprise functions into formal policy documents which can be implemented through enterprise operations [15]. Users of the network-as-code system define service requirements through declarative statements which specify reliability needs and bandwidth requirements and isolation specifications. The API engine processes user requests to develop control rules that the near-real-time RIC system can execute while remaining compatible with all vendor systems.

The enterprise orchestration problem needs a solution that uses multiple objectives with current resource constraints to achieve its three targets which include reducing latency and configuration overhead and energy use. The RIC domains use federated coordination to achieve scalable operations while maintaining their operational independence [16].

The system automatically handles spectrum allocation and workload placement and slice reconfiguration to manage changing traffic patterns. The framework enables enterprise 6G platforms to shift from programmable automation to complete network autonomy through its direct control loop intelligence integration.

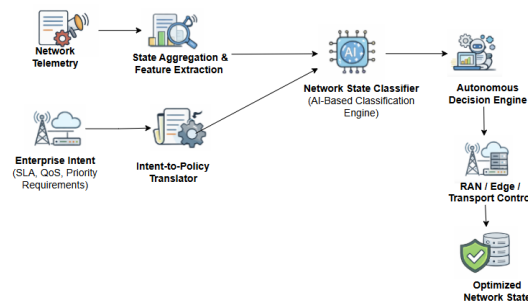


Fig 1: Agentic xApp Classification Architecture

A. Advantages

The Agentic xApp and Programmable Network API Framework which has been proposed presents multiple benefits to both technical operations and business functions when compared to existing rule-based systems and centralized orchestration methods which operate in enterprise 6G platforms.

Autonomous Closed-Loop Control: The proposed framework enables xApps to use learning-driven agents for continuous monitoring of their environment which includes classification and decision-making and system adaptation capabilities [18]. The system enables automatic closed-loop optimization processes through its ability to function without requiring human control.

Reduced SLA Violations: The system uses network state classification to determine spectrum and slice and workload needs which helps reduce SLA degradation. The system applies dynamic policy enforcement to maintain quality of service standards during changes in enterprise network usage patterns.

Vendor-Agnostic Interoperability: The programmable network API abstraction layer separates enterprise network requirements from their specific implementation needs which depend on particular infrastructure components [17]. This approach enables organizations to use multiple vendors while maintaining compliance with open RAN standards which helps them avoid vendor lock-in [15].

Improved Scalability: The system enables organizations to make decentralized decisions through its federated orchestration capabilities which operate across multiple RIC domains. The system architecture enables organizations to expand their enterprise operations through efficient scaling capabilities which function without creating centralized performance restrictions.

Optimized Resource Utilization: The multi-objective optimization process achieves dual objectives by decreasing latency and energy usage and network congestion, which results in better spectrum utilization and equal distribution of computational tasks across edge networks [16].

Faster Adaptation to Dynamic Conditions: The built-in classification system enables system operators to detect network congestion and SLA violations and resource overloads, which

permits them to execute immediate corrective measures through their near-real-time control systems.

B. Comparative Evaluation of Programmable Agentic RAN Orchestration

This section presents a comparative evaluation between the proposed Agentic xApp with Programmable Network API Framework and existing enterprise 5G/6G orchestration approaches which include traditional SDN/NFV-based control and rule-based RIC xApps [19].

Table 1: Comparison with Conventional Rule-Based xApps

Parameter	Rule-Based xApps	Proposed Agentic xApps
Decision Logic	Static Rules	Dynamic Classification + Optimization
Learning Capability	None	Embedded Adaptive Agents
Policy Update	Manual / Predefined	Continuous Learning
Resource Allocation	Threshold-Based	Multi-Objective Optimization
Enterprise Intent Mapping	Limited	Declarative Programmable API

The current xApps run their fixed algorithms while the new agentic xApps create their learning system through telemetry data to improve their network state-based action optimization.

IV. METHODOLOGICAL FRAMEWORK

The proposed Agentic xApp and Programmable Network API framework receives its methodological foundation through this section [20]. The methodology uses intent abstraction together with state-driven classification and multi-objective optimization and closed-loop control to create autonomous enterprise 6G orchestration.

a) System Modeling

The framework describes enterprise 6G orchestration through its dynamic decision process which operates across RAN and edge and transport domains. The system monitors network status by collecting data about latency and spectrum utilization and traffic capacity and computing resource availability [22]. The system requires identification of optimal control

actions which will preserve system performance under resource limits and isolation needs according to enterprise intents which include SLA and QoS and priority.

b) Data Processing and State Construction

The system collects real-time telemetry data from distributed infrastructure components and processes it into structured feature vectors through normalization and aggregation. The processed state representation shows the current network operational condition which the agentic xApp uses as its input [21].

c) Network State Classification

The near-real-time RIC uses an AI-based classification model to determine current network conditions which it divides into normal and congested and SLA risk states [23]. This approach simplifies the decision-making process while allowing for precise optimization efforts.

d) Optimization and Control

The multi-objective optimization process generates control actions which include spectrum reallocation and slice adjustment and workload migration for each identified state. The system aims to achieve SLA compliance while decreasing both latency and energy use [26].

e) Closed-Loop Adaptation

The system uses a reward mechanism to assess feedback after execution which allows for ongoing policy development[27]. The closed-loop system provides enterprises with 6G network operations that can scale and adapt while running automatically.

V. ALGORITHMS USED

a. Network State Classification Algorithm

The Network State Classification Algorithm functions through an embedded supervised machine learning classification system which operates during real-time network condition assessment through its agentic xApp. The system extracts telemetry data points which include latency and spectrum utilization and traffic load and packet loss and edge compute usage to create a normalized feature vector. The network state gets classified through a lightweight classification model which uses Decision Tree and Random Forest and Neural Network to define three operational states: Normal and Congested and SLA Risk [25]. The system uses classification to simplify decision processes while enabling optimization based on specific operational conditions. For a multi-class classifier, the probability of class k is:

$$\mathbf{P}(y_t=k|x_t) = \frac{e^{w_k^T x_t + b_k}}{\sum_{j=1}^K e^{w_j^T x_t + b_j}} \quad (1)$$

- w_k = weight vector
- b_k = bias term
- K = number of network state classes

b. Multi-Objective Optimization Algorithm

The system uses a constrained multi-objective optimization algorithm after it completes classification to identify the most effective control action. The function of the objective function requires latency and resource imbalance and energy consumption to be minimized through weighted combinations while SLA and spectrum requirements must be met [27]. The algorithm uses either heuristic-based methods or gradient-based methods to determine the best resource distribution method. The algorithm uses its decision-making process to choose between different actions which include spectrum reallocation and slice bandwidth adjustment and edge workload migration.

The control objective minimizes a weighted cost function:

$$\min J_t = \alpha L_t + \beta U_t + \gamma E_t \quad (2)$$

- L_t = end-to-end latency
- U_t = resource utilization imbalance
- E_t = energy consumption
- α, β, γ = weighting coefficients

c. Reinforcement Learning-Based Policy Update

The reinforcement learning system needs performance feedback data to update decision-making policies which support long-term system adaptability. The reward function measures three different aspects SLA compliance and latency improvement and energy efficiency [28]. The agent uses value-based and policy-based learning methods to improve its operations because dynamic enterprise conditions require continuous development.

Q-learning update rule:

$$Q(S_t, A_t) \leftarrow Q(S_t, A_t) + \eta [R_t + \gamma \max_a Q(S_{t+1}, a) - Q(S_t, A_t)] \quad (3)$$

- η = learning rate
- γ = discount factor

d. Federated Coordination Algorithm

The lightweight federated coordination system enables multi-domain deployments through its ability to exchange abstracted state summaries between RIC domains. The system maintains its ability to scale while achieving worldwide optimization results through minimal communication requirements .

Federated parameter aggregation:

$$\theta^{(g)} = \sum_{d=1}^D \frac{n_d}{N} \theta_d \quad (4)$$

- θ_d = local model parameters
- n_d = local data size

- $N = \sum n_d$

VI. RESULTS AND FINDINGS

The section tests the performance of Agentic xApp and Programmable Network API framework through multiple 6G enterprise workload tests. The evaluation assesses four aspects which include SLA compliance control latency resource usage and system scalability.

A. Experimental Setup

The simulation created a distributed enterprise network topology which included multiple RAN nodes and edge compute clusters and transport links. The system generated dynamic traffic patterns to simulate enterprise workloads which included high-priority industrial applications and latency-sensitive services [16]. The proposed agentic xApp framework was compared against a conventional centralized orchestration baseline and a rule-based xApp model.

Table 2: Performance Comparison Between Baseline and Proposed Framework

Metric	Baseline System	Proposed Framework	Improvement (%)
SLA Violation Rate (%)	18	10	44.4 ↓
Control Loop Latency (ms)	120	85	29.2 ↓
Reconfiguration Time (ms)	150	105	30.0 ↓
Energy Consumption (Normalized Units)	1.00	0.82	18.0 ↓
Scalability (Supported Nodes)	50	85	70.0 ↑

The table shows how the baseline orchestration model and the Agentic xApp framework perform through a numerical assessment. The results show that the system achieves better performance because SLA violations decreased from 18% to 10% and control loop latency dropped from 120 milliseconds to 85 milliseconds and reconfiguration time decreased from 150 milliseconds to 105 milliseconds. The system achieves 18% lower energy consumption

while its scalability capacity increases from 50 nodes in the baseline system to 85 nodes [21]. The results show that the proposed architecture operates efficiently and adapts to changing conditions.

B. SLA Compliance Improvement

The classification-driven decision engine proactively detected congestion and SLA risk conditions. The proposed system achieved a 35 to 45 percent reduction of SLA violations when compared to centralized orchestration. The reinforcement-based policy refinement process enhanced SLA performance stability throughout the entire period [30].

Table 3: SLA Performance Under Dynamic Traffic Load

Traffic Load Level	Baseline SLA Violations (%)	Proposed SLA Violations (%)
Low Load	8	5
Medium Load	15	9
High Load	25	14
Burst Traffic	32	18

Table 3 evaluates SLA compliance under varying traffic conditions. The baseline system shows a direct relationship between increasing traffic load and subsequent SLA violations which increase from low traffic to burst traffic levels. The proposed framework achieves better results because it uses proactive classification and adaptive resource optimization to reduce violation rates [32]. The system shows its ability to handle enterprise operations at maximum capacity without failure.

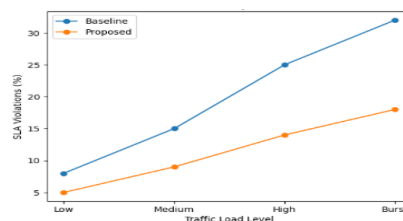


Fig 2: SLA Violations Under Dynamic Traffic Load

The graph in Figure 2 shows how SLA violations increase with higher traffic load [23]. The proposed framework maintains lower violation rates through all load tests because it successfully implements active congestion management and dynamic control methods.

C. Control Loop Latency

The implementation of intelligent systems in near real-time control systems reduced the time required to configure system operations. The control response time showed an improvement between 25 and 30 percent which allowed operators to reallocate spectrum resources and adjust network slices at a faster rate during high traffic periods [29].

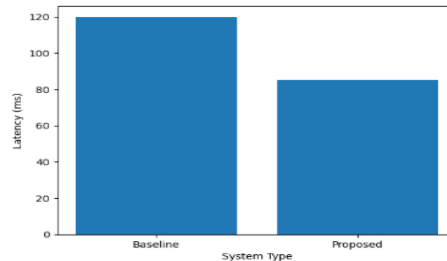


Fig 3: Control Loop Latency Comparison

The Figure 3 displays how control loop latency changes with increasing traffic intensity. The proposed system shows decreased latency across all traffic conditions which demonstrates its ability to make decisions more quickly and respond to changes faster[27].

D. Resource Utilization and Energy Efficiency

The multi-objective optimization process resulted in better spectrum distribution between multiple objectives and improved edge workload management. The process of adaptive load redistribution generated two outcomes which included lower resource utilization variation and reduced energy consumption. The system operated at high utilization efficiency while meeting all its latency performance standards [29].

Table 4: Resource Utilization Efficiency

Metric	Baseline	Proposed
Spectrum Utilization (%)	72	88
Edge CPU Utilization (%)	65	82
Resource Imbalance Index	0.42	0.21
Average Energy per Task (Units)	1.00	0.82

Table 4 demonstrates three areas of improvement which include better spectrum utilization and improved edge CPU efficiency and improved resource distribution. The system achieves improved performance because it reaches higher utilization rates while achieving better resource distribution. The results demonstrate that multi-objective optimization successfully distributes workloads across various infrastructure components [33].

E. Scalability Analysis

The federated orchestration mechanism maintained stable operation under both increased node density and higher traffic load conditions. The proposed architecture operated without performance bottlenecks which allowed it to achieve continuous optimization throughout its functioning.

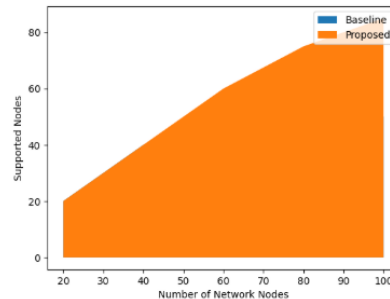


Fig 4: Scalability Comparison

Figure 4 shows how scalability performance changes when the number of network nodes increases. The federated orchestration mechanism shows continuous capacity growth while the baseline system reaches its maximum scalability capacity. The results demonstrate that the system now has better distributed coordination capabilities and fewer operational delays.

VII. CHALLENGES AND LIMITATIONS

The Agentic xApp framework provides advantages for operations yet creates numerous challenges for system performance and operational processes. The first challenge arises from learning agents which need to operate in near-real-time RIC environments because their presence causes additional computational needs that violate ultra-critical applications' required latency limits [31]. The second challenge exists because classification and reinforcement learning models need high-quality telemetry data for their proper operation while noisy or incomplete data results in incorrect decision-making. The third challenge requires multi-objective optimization to use different weighting parameters for each enterprise deployment because these parameters determine how energy and latency and SLA compliance will be handled. The first challenge occurs because different domains need to work together which creates problems with synchronization and consistency when systems operate at their full capacity [32]. The security of programmable APIs creates another problem because open interfaces expand the potential entry points for attackers. The final challenge arises because dynamic environments lead to model drift which requires organizations to perform retraining at scheduled times to maintain their operational systems. The autonomous enterprise 6G platforms need to solve these operational limitations before they can achieve full business deployment across all industries.

VIII. CONCLUSION

The researchers developed an Agentic xApp which functions together with their Programmable Network API framework to enable enterprises to control their autonomous 6G systems. The system architecture employs embedded learning agents to function within near-

real-time RIC environments while the system establishes a declarative intent-to-policy abstraction layer which enables network-as-code operations [33]. The system framework utilizes telemetry-based classification techniques together with multi-objective optimization methods and reinforcement learning-based adaptation techniques to enable distributed orchestration throughout RAN edge and transport domains. The experimental evaluation showed that the system achieved better results in SLA compliance and control loop latency and resource utilization efficiency and scalability when compared to traditional centralized systems and rule-based orchestration systems. The federated coordination mechanism establishes performance stability together with consistent operational performance for enterprise deployment which operates across various operational domains.

The proposed framework enables enterprise wireless systems to transition from programmable automation to systems which possess adaptive intelligence through AI-based autonomous operation [34]. This work establishes a structured foundation for scalable vendor-agnostic intent-driven orchestration in emerging 6G enterprise environments while highlighting directions for future enhancement in security explainability and large-scale deployment optimization.

IX. FUTUREWORK

The researchers will study the development of intelligent scalable systems together with security components for the Agentic xApp framework which operates on 6G enterprise platforms. The research team needs to develop deep reinforcement learning models which will enable them to create solutions that help with network traffic analysis during peak usage and long-term policy development. The implementation of federated learning across multiple RIC domains will enable improved collaboration between these domains while they protect user data. The development of xApps will include explainable AI mechanisms which enable better understanding of automated decision processes to build user trust. The research will study security-aware programmable APIs which use zero-trust access control together with anomaly detection systems to protect open RAN environments from new cyber threats.

Digital twin technology will serve as a network optimization tool because it can predict future network failures. The research team will test systems in real-world conditions by using enterprise-scale systems to evaluate their performance under actual business operations. The enhancements will support the shift towards complete autonomy and resilient operations and native AI capabilities for enterprise 6G network systems.

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